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((ACLM/"automatic transmission" AND ACLM/position) AND SPE	C/GPS): 16 patents.
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ACLM/"automatic transmission" AND ACLM/position

PAT. Title NO.

6,920,384 Driving force control apparatus for vehicle

- 6,830,534 Method for controlling the internal combustion engine of a motor vehicle with a stop/start function
 - 6,740,002 Hybrid powertrain
- 6,516,261 Control system for automatic vehicle transmissions
- 6,403 125 Parked vehicle locator
- 6,351,698 T Interactive vehicle control system
- 7 6,292,736 T Vehicle control system and recording media recorded with programs for the system
- 8 6,278,928 Transmission control device responsive to road information
- 9 6,220,986 T Vehicle control system for suppressing shift determinations at a corner using road data
- 10 6,098,005 T Vehicle transmission controller for changing gear ratios in accordance with road features
- 11 6,085,137 T Vehicle control device
- 12 6,083,248 World wide patient location and data telemetry system for implantable medical devices
- 13 6.016.457 T Vehicle drive force controller
- 14 6,014,605 T Vehicular control system for detecting road situations of a planned route
- 15 5,893,894 T Apparatus for controlling an automatic transmission of an automobile and method thereof
- 16 5,39\2,052 \ Position reporting emergency location system

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Patent Database Search Results: ACLM/"automatic transmission" AND ACLM/position ... Page 2 of 2

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Set 51	Items 181 4	Description TRANSMISSION AND GPS AND POSITION? AND PD<=010330 S1 AND (AUTOMATIC? (S) TRANSMISSION?)
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T 54/3, KWIC/1

4/3,KWIC/1 (Item 1 from file: 95)
DIALOG(R)File 95:TEME-Technology & Management
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01370996 19991200515

Multiple-observer scheme for safe navigation

(Positionsmessung mit einer Beobachterstruktur, bestehend aus mehreren Sensoren, fuer die sichere Navigation in der Schifffahrt) Schultze, R
FH Konstanz, D
Control Engineering Practice, v7, n10, pp1279-1289, 1999
Document type: journal article Language: English
Record type: Abstract
ISSN: 0967-0661

(Positionsmessung mit einer Beobachterstruktur, bestehend aus mehreren Sensoren, fuer die sichere Navigation in der Schifffahrt) 1999

ABSTRACT:

...problems encountered at many sensors, transient failures like pauses, jumps or ramps and asynchronous data transmission with variable latency. The navigation filter utilizes a bank of observers that is dynamically rearranged...

...of currently available sensor data. The availability and safety improvement of the approach is the automatic fault-detection with immediate switch-over to a backup (standby) observer, which has already converged...

...instance to mobile robots working indoors and outdoors with changing availability and accuracy of sensors (GPS (Global Positioning System) only outside, wheel sensors work better inside on a flat floor). IDENTIFIERS: MEHRSENSORENSYSTEM; Navigation; Positionsmessung; Beobachter; Mehrfachsensor

T S2/3, KWIC/1-4

2/3,KWIC/1 (Item 1 from file: 34) DIALOG(R) File 34: SciSearch(R) Cited Ref Sci (c) 2005 Inst for Sci Info. All rts. reserv.

No. References: 11 Genuine Article#: 438FZ Title: The design of mobile multimodal communication device - Personal

Author(arepsilon): Kotnik B; Kotovnik T; Kacic Z; Horvat B; Horvat B; Kramberger I Corporate Source: Univ Maribor, Inst Elekt, Fakulteta Elektrotehn

Racunalnistvo Informat, SLO-2000 Maribor//Slovenia/

Journal: INFORMACIJE MIDEM-JOURNAL OF MICROELECTRONICS ELECTRONIC COMPONENTS AND MATERIALS, 2001, V31, N1 (MAR), P39-47 N: 0352-9045 Publication date: 20010300

ISSN: 0352-9045

Publisher: SOC MICROELECTRONICS, ELECTRON COMPONENTS MATERIALS-MIDEM,

DUNAJSKA 10, LJUBLJJANA 61000, SLOVENIA

Language: Slovak Document Type: ARTICLE (ABSTRACT AVAILABLE)

Publication date: 20010300

... Abstract: with touch-panel. Speech communication is supported by a powerfull digital signal processor, which makes automatic recognition and the synthesis of speech possible. That way, the personal navigator

...connected to the device, together with a combined microphone. The concept alone also includes image transmission, connection to the Internet and positioning - using Global Positioning System. Personal navigator also needs a navigation server (Pic.2), which runs on a PC. Combined GPS /GSM module /3/ is connected to the server. The GPS module in the navigation server is needed for implementation of differential positioning; GSM module serves for establishing data connection with Personal navigator.

The current testing implementation of personal navigator (Pic.3), combines GPS unit for establishing position of the user. It consists of GPS receiver module and a GPS unit processormicrocontroler AT90S2313. The microcontroler communicates with the central processor Atmega 103 through a...

...information and a communication device. As a tourist guide it informs the user about his position , displays the interesting tourist sights, tourist information and tourist guiding. Besides the above-mentioned, it...

2/3,KWIC/2 (Item 2 from file: 34)

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Genuine Article#: 403UQ No. References: 13

Title: Centimeter-level positioning on the seafloor

Author(s): Asada A (REPRINT) ; Yabuki T

Corporate Source: Univ Tokyo,Inst Ind Sci, Meguro Ku,4-6-4 Komaba/Tokyo 1538505//Japan/ (REPRINT); Univ Tokyo, Inst Ind Sci, Meguro Ku, Tokyo 1538505//Japan/; Japan Coast Guard, Dept Hydrograph, Chuo Ku, Tokyo 1040045//Japan/

Journal: PROCEEDINGS OF THE JAPAN ACADEMY SERIES B-PHYSICAL AND BIOLOGICAL SCIENCES , 2001, V77, N1 (JAN), P7-12

ISSN: 0386-2208 Publication date: 20010100

Publisher: JAPAN ACAD, 7-32 UENO PARK, TOKYO, 110, JAPAN

Language: English Document Type: ARTICLE (ABSTRACT AVAILABLE)

Title: Centimeter-level positioning on the seafloor Publication date: 20010100

... Abstract: method for the seafloor geodes is under development in order to overcome several difficulties. The position of the ea-bottom transponders at the vicinity of the Nankai trough and the Japan Trench is observed using a GPS /Acoustic measurement system. Early results from processed data show a scatter of 4 cm standard deviation for repeated horizontal positioning from drifting survey vessel. This paper describes tow techniques developed to realize precise acoustic ranging, automatically detecting and correcting the Doppler-shift of acoustic propagation signal due to ship's drifting and attitude motion, and theoretically forming a pulse of one wavelength in cross

correlation between transmission and reception of long-coded signals.

2/3,KWIC/3 (Item 1 from file: 61)

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0000174437 IP ACCESSION NO: A2004-61-00343

Development of a GPS Active Control Point Station

Quek, S.H.; Craymer, M.; Langley, R.B.; Parkhill, D.; Arseneau, D.; McArthur, D.; Lochhead, K.

Journal of Surveying Engineering, v 115, n 1, p 46-55, Feb. 1989 PUBLICATION DATE: 1989

PUBLISHER: American Society of Civil Engineers, 1801 Alexander Bell Drive,

Reston, VA, 20191-4400

COUNTRY OF PUBLICATION: USA

PUBLISHER URL: http://www.asce.org

PUBLISHER EMAIL: journal-services@asce.org

DOCUMENT TYPE: Journal Article

RECORD TYPE: Abstract LANGUAGE: English ISSN: 0733-9453

FILE SEGMENT: Civil Engineering Abstracts

Development of a GPS Active Control Point Station

, Feb. 1989

ABSTRACT:

... of the Active Control System, a project to establish a nationwide network of automated Global Positioning System (GPS) tracking stations, or active control points (ACPs). Benefits from such a network include improved integrity, precision and economics of both differential static and kinematic positioning applications using GPS, and independent orbit determination and refinement. A prototype ACP station has been constructed to test...

...communications line are also interfaced to the computer. The station is capable of unattended operation, automatic satellite tracking, and the acquisition, decoding, validation and transmission of data to the remote Master Active Control Station (MACS). The ACP station can be...

DESCRIPTORS: Global positioning; Geodetic surveys; Satellites; Mapping; Surveys

2/3,KWIC/4 (Item 1 from file: 95)

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01370996 19991200515

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...of currently available sensor data. The availability and safety improvement of the approach is the automatic fault-detection with

immediate switch-over to a backup (standby) observer, which has already converged...

...instance to mobile robots working indoors and outdoors with changing availability and accuracy of sensors (GPS (Global Positioning System) only outside, wheel sensors work better inside on a flat floor).

IDENTIFIERS: MEHRSENSORENSYSTEM; Navigation; Positionsmessung; Beobachter; Mehrfachsensor

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